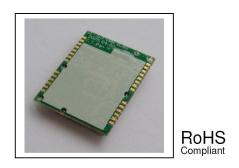


# GPS Engine Board UR-91

Ublox-6

# User Manual







#### **Product Information**

Product Name: UR-91 Product Description:

UR-91 is a compact, high performance, and low power consumption GPS engine board.

It uses ublox 6 chipset which can track up to 16 satellites and 50 channels at a time and perform fast TTFF in weak signal environments. UR-91 is suitable for the following applications:

- Automotive navigation
- Personal positioning
- Fleet management
- Mobile phone navigation
- Marine navigation

#### **Product Features:**

ublox 6 high performance and low power consumption GPS Chipset

Very high sensitivity (Tracking Sensitivity: -160 dBm)

Extremely fast TTFF (Time To First Fix) at low signal level

One serial port and one usb port

Built-in LNA

3Mbit of internal ROM and 2Mbit of RAM

Compact size (17mm \* 22.4mm \* 3.0mm) suitable for space-sensitive application

One size component, easy to mount on another PCB board

Support NMEA 0183 and ublox binary protocol

#### **Product Specifications**

#### **GPS Receiver**

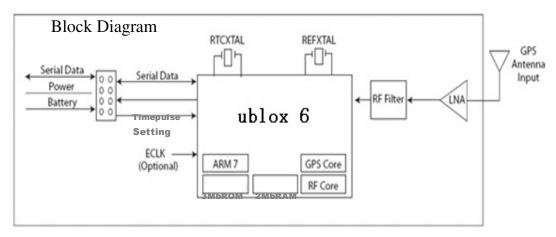
Chipset	ublox UBX-G6010
Frequency	L1, 1575.42 MHz
Code	C/A Code
Protocol	NMEA 0183 v2.3
	GALILEO L1 open service(with upgrade)
	Default:GGA,GSA,GSV,RMC
	Support:VTG,GLL,TXT



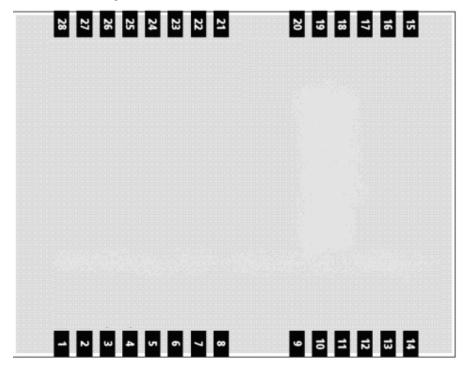
	ublox binary and NMEA Command	
	GOOD OTHER Y AND INVIEW COMMISSION	
Available Baud Rate	9,600 bps or others by optional	
Channels	50	
Internal ROM	3Mbit of ROM and 2Mbit of RAM	
Sensitivity	Tracking:-160dBm Reacquisition:-160dBm ColdStart:-146dBm	
Cold Start	29 seconds, average	
Warm Start	29 seconds, average	
Hot Start	1 second, average	
Accuracy	HorizontalPosition:Autonomous<2.5maverage, SBAS < 2.0m average Velocity: 0.1 m/s Time pulse signal: RMS 30 ns	
Maximum Altitude	18,000 meter	
Maximum Velocity	515 m/s(1000 knots)	
Dynamics	≦ 4G	
Update Rate	4 Hz	
A-GPS	AssistNow on-line and off-line	
Interface		
I/O Pins	1 serial port/1 usb port	
Physical Characteristic		
Туре	28-pin stamp holes	
Dimensions	22.4mm * 17.0 mm * 3.0 mm ±0.1mm	
DC Characteristics		
Power Supply	3.3VDC ± 5%	
Backup Voltage	1.8~3.6VDC	
Power Consumption	Max Performance: Acquisition:49mA; Tracking: 42mA Eco Mode: Acquisition:48mA; Tracking:38mA Power Save Mode: 16mA	
Environmental Range		
Humidity Range	5% to 95% non-condensing	
Operation Temperature	-40°C to 80°C	
Storage Temperature	-40°C to 80°C	



## 2. Technical Information



## Module Pin Assignment:

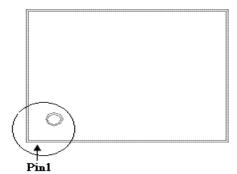


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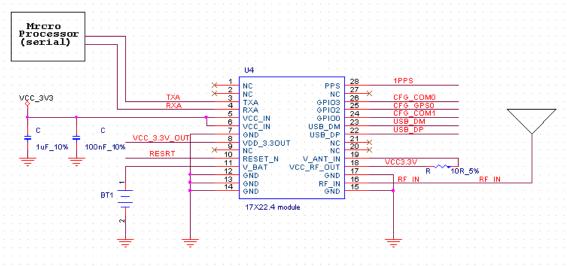
Pin NO.	Pin Name	I/O	Remark
1	NC	Х	Reserve
2	NC	Х	Reserve
3	TXA	0	This is the main transmits channel for outputting navigation and measurement data to user's navigation software or user written software.Output TTL level, 0V ~ 2.85V.
4	RXA	I	This is the main receive channel for receiving software commands to the engine board from ublox demo software or from user written software.
5	VCC	PWR	Main power supply to the engine board.
6	VCC	PWR	Main power supply to the engine board.
7	GND	G	Ground.
8	VCC_3.3_VOUT	PWR	Output voltage 3.3V
9	NC	Х	Reserve
10	Reset	ı	Reset (Active Low)
11	VBAT	PWR	Backup battery supply voltage
12	NC	Х	Reserve
13	GND	G	Ground.
14	GND	G	Ground.
15	GND	G	Ground.
16	RF IN	I	GPS antenna input
17	GND	G	Ground.
18	VCC_RF_OUT	0	Supply Antenna Bias voltage(3.3V)
19	V_ANT_IN	ı	Active Antenna Bias voltage
20	NC	Х	Reserve
21	NC	Х	Reserve
22	USB_DP	I/O	USB I/O LINE
23	USB_DM	I/O	USB I/O LINE
24	Setting	S	CFG_COM1( Baud rate setting)
25	Setting	S	CFG-GPS0(Power mode setting, OPEN=Maxmize performance mode; GROUND=Eco mode)
26	Setting	S	CFG_COM0 ( Baud rate setting)
27	NC	Х	Reserve
28	Timepulse	0	One pulse per second







## **Application Circuit**



PS: OPEN=1 GND=0

CFG_COM1	CFG_COMD		MASSAGE	BAUD-RATE
i	· · · · i · ·	NMEA	GSV, RMC, GSA, GGA, GLL, VTG, TXT	9600
<sub>1</sub> .				38400
	· · · · i · · ·		GSV, RMC, GSA, GGA, VTG, TXT	4800
		UBX -		

#### **GPS Active Antenna Specifications (Recommendation)**

Frequency: 1575.42 + 2MHzAxial Ratio: 3 dB Typical Output Impedance:  $50\Omega$ Polarization: RHCP

Amplifier Gain: 15~20dB Typical

Output VSWR: 2.0 Max. Noise Figure: 2.0 dB Max

Website: www.progin.com.tw

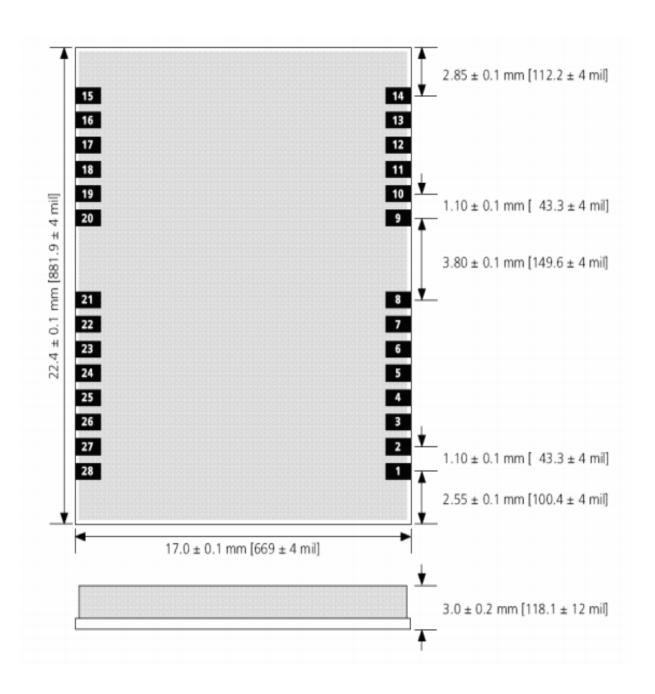
Antenna Input Voltage: 3.3V (Typ.)

**Dimensions** 



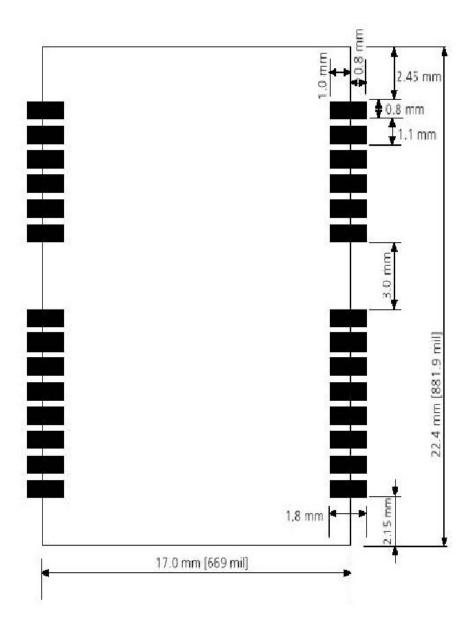
Website: www.progin.com.tw

## UR-91





## Recommended Layout PAD



Unit: mm

Tolerance: 0.1mm



## **UR-91 Application Guideline**

#### **Lavout Rules**

Do not routing the other signal or power trace under the engine board .

#### \* RF:

This pin receives signal of GPS analog via external active antenna .It has to be a controlled impedance trace at 50ohm.

Do not place the RF traces close to the other signal path and not routing it on the top layer. Keep the RF traces as short as possible.

#### \* Antenna:

Keep the active antenna on the top of your system and confirm the antenna radiation pattern \( \) axial ratio \( \) power gain \( \) noise figure \( \) VSWR are correct when you Setup the antenna in your case.

#### **GPS Passive (or Active ) Antenna Specifications(Recommendation)**

Frequency: 1575.42±2 MHz Axial Ratio: 3 dB Typical Output Impedance: 50Ω Polarization: RHCP Output VSWR: 1.5 Max.

**Active option** 

#### **Low Noise Amplifier:**

Website: www.progin.com.tw

Amplifier Gain:16~20dB Typical

Output VSWR: 2.0 Max. Noise Figure: 2.0 dB Max.

Antenna Input Voltage: 3.3V Typical



#### **Design Notes**

#### **VCC**

This is the main power supply to the engine board.  $(3.3 \text{Vdc} \pm 5\%)$ 

#### **GND**

Ground pin for the baseband circuit.

#### **RXA**

This is the main channel for receiving software commands from u-blox software or from your proprietary software.

#### **TXA**

This is the main transmits channel for outputting navigation and measurement data to user's navigation software or user written software.

Output TTL level,  $0V \sim 2.85V$ 

#### RF IN

This pin receives signal of GPS analog via external active antenna. It has to be a controlled impedance trace at 50ohm. Do not have RF traces closed the other signal path and routing it on the top layer. Keep the RF traces as short as possible.

#### **VBAT**

This is the battery backup power input for the SRAM and RTC when main power is removed. Typical, the current draw is 15uA. Without the external backup battery, the module/engine board will always execute a cold start after turning on. To achieve the faster start-up offered by a hot or warm start, a battery backup must be connected. The battery voltage should be between 1.8v and 3.6v.

#### Time pulse

1 pulse per second synchronized at rising edge pulse length 100ms



#### CFG\_GPSO

The system power modes can be configured at the CFG\_GPSO pin

PIO21 / CFG_GPS0	GPS mode
1	Maximum Performance Mode XTO.
0	Eco Mode XTO.

## Wake Up

This pin will used in future functions in low-power modes.

## CFG\_COM0 and CFG\_COM1

The baud rate of the communication interface can be configured using the **CFG\_COM** pins as follows

PIO20 / CFG_COM1	PIO19 / CFG_COM0	Protocol	Messages	UART1/2 Baud rate
1	1	NMEA	GSV, RMC, GSA, GGA, GLL, VTG, TXT	9600
1	0			38400
0	1		GSV <sup>1</sup> , RMC, GSA, GGA, VTG, TXT	4800

#### DM and DP

USB bidirectional communication pin. The u-blox USB interface supports the full-speed data rate of 12 Mbit/s.